

Using Matlab as a Solver for Validation

In this lab, you will be using MagicDraw to determine if a set of requirements can be achieved for a simple system. As we saw last week, Mathematica can be used as a solver with MagicDraw to automatically solve a set of constraints. In this week's lab, you will be using Matlab as the solver and it will be up to you how to structure the requirements diagrams, the block diagrams, the parametric diagrams and the instance diagram using last week's exercise as a guideline. There are many ways in which this can be accomplished and there is no one right answer.

Problem Statement

The customer wishes to use a pendulum clock to keep track of time. His requirement is that the clock loses no more than a second every hour.

Requirement: The clock loses no more than one second every hour.¹

Description of Pendulum

A simple model for pendulums indicates that the period is given by the expression $T = 2\pi\sqrt{\frac{l}{g}}$ where l is the length of the pendulum and g is the gravitational constant². The length of the pendulum will be given by

$$l = g \left(\frac{T}{2\pi} \right)^2$$

where $T = 2$ is a convention that will make the length of the pendulum $l = \frac{g}{\pi^2}$ very close to 1.

However, the above is just an approximation valid for very small angles of oscillation. The actual period is a more complex expression that is dependent on the range of oscillation. In this exercise we do make some other simplifying assumptions, such as lack of friction and a perfectly rigid pendulum with a point mass at the end, but we will be investigating under what conditions it will be possible to satisfy the above requirements.

The equation for pendulum motion is given by

$$\ddot{\theta} = -\frac{g \sin \theta}{l}.$$

Which can also be written as

$$\begin{aligned} \dot{\theta} &= \omega \\ \dot{\omega} &= -\frac{g \sin \theta}{l}. \end{aligned}$$

Matlab Pendulum Model

The pendulum will be modeled in Matlab and will have two input parameters, the length and the angle, and one output parameter, the period. Instructions on creating the model are given below.

This will be how the pendulum is modeled in Matlab. Create an mfile called "pendulum.m" with the following contents.

```
function xdot = pendulum(len, t, x)
xdot = [x(2); -9.81*sin(x(1))/len]
```

Here x is the state vector standing for $\langle \theta, \omega \rangle'$. Matlab will use this description to solve the system.

Create an additional mfile called "zeroevent.m" with the following contents.

```
function [lookfor stop direction] = zeroevent(t,x)
lookfor = x(1);
stop = 1;
direction = -1;
```

¹Hint: a requirement diagram can be used to capture this, but an additional constraint might be needed to model it.

² g is assumed to be $9.81 \frac{\text{m}}{\text{s}^2}$

This file instructs Matlab's differential equation solver to look for $\theta = 0$ and to stop when it occurs, with θ having a negative derivative.

This next mfile should be called "computePeriod.m" and will call the ode solver to determine the period.

```
function period = computePeriod(len , angle )
x0 = [ angle *(pi ()/180) ,0];
findEvent = odeset('Events' , @zeroevent);
[t,x,te,xe,ie]=ode45(@(t,x)pendulum(len,t,x), [0,5], x0, findEvent);
period = 4*te;
```

Finally, to link the created model to MagicDraw UML, create a Matlab script called "periodscript.m".

```
insel = load('input.txt ');
len = insel(1);
angle = insel(2);
period = computePeriod(len , angle );
save('output.txt ', 'period ', '-ASCII ');
exit
```

Linking the Matlab Model to a Constraint When creating the Constraint Block that will capture the pendulum behavior, follow the instruction 4-6 that begin on page 48 of the Paramagic User Manual. In step 4.5, use the following settings.

output Parameter: period

script_or_function: scriptascii

name_of_m-file: periodscript.m

input1: length

input2: angle

This links the constraint to the Matlab model.

Questions

1. Create a requirements diagram (showing how the requirements are verified), a block diagram showing the structure, as many parametric diagrams as necessary, and instance diagrams as needed to describe this problem.
2. Explore different values for the starting angle and see if you can determine a range over which the customer's demands are feasible.