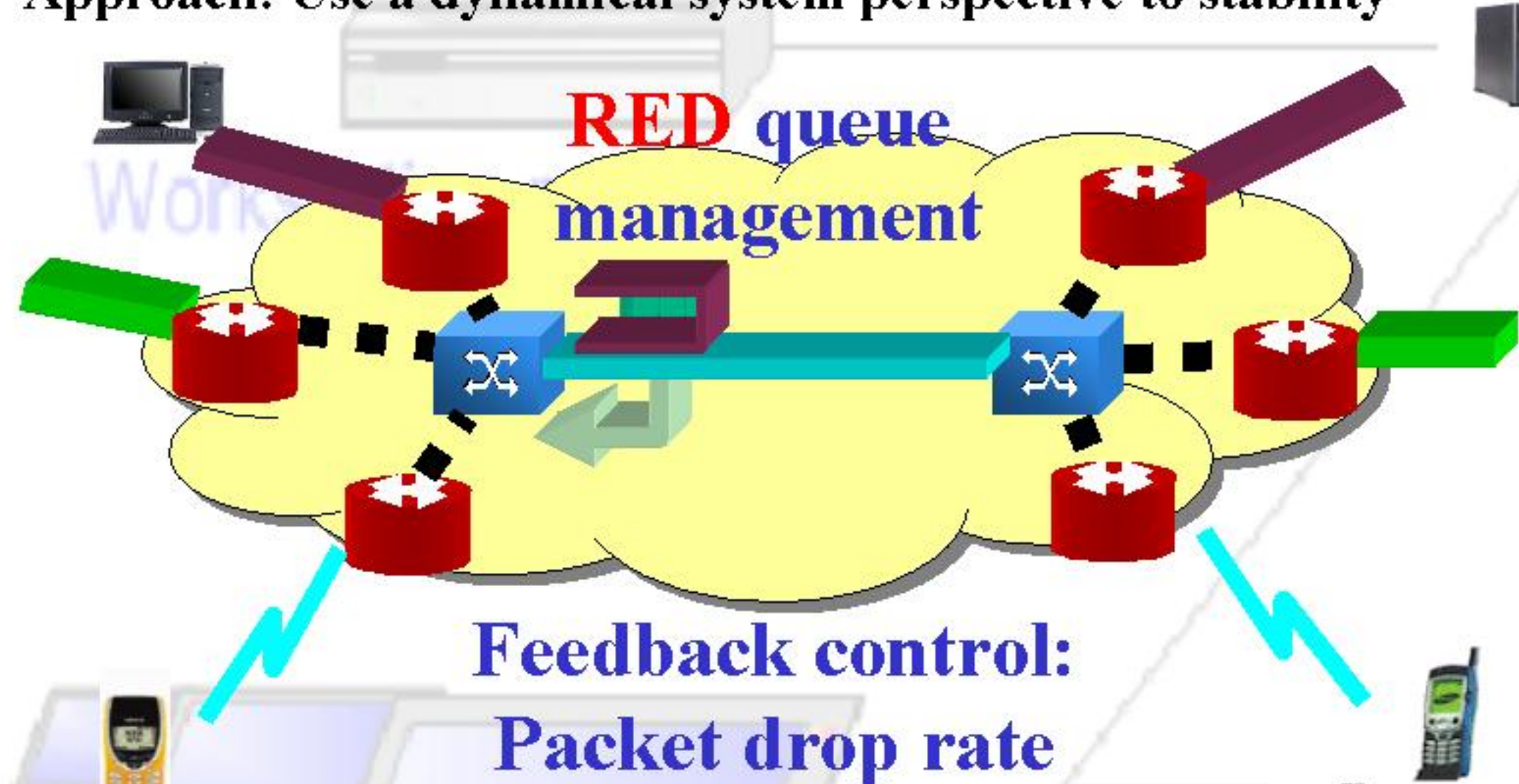


Priya Ranjan/ Eyad Abed, Richard La

**Problem:** How to set RED parameters in a robust way?

**Approach:** Use a dynamical system perspective to stability

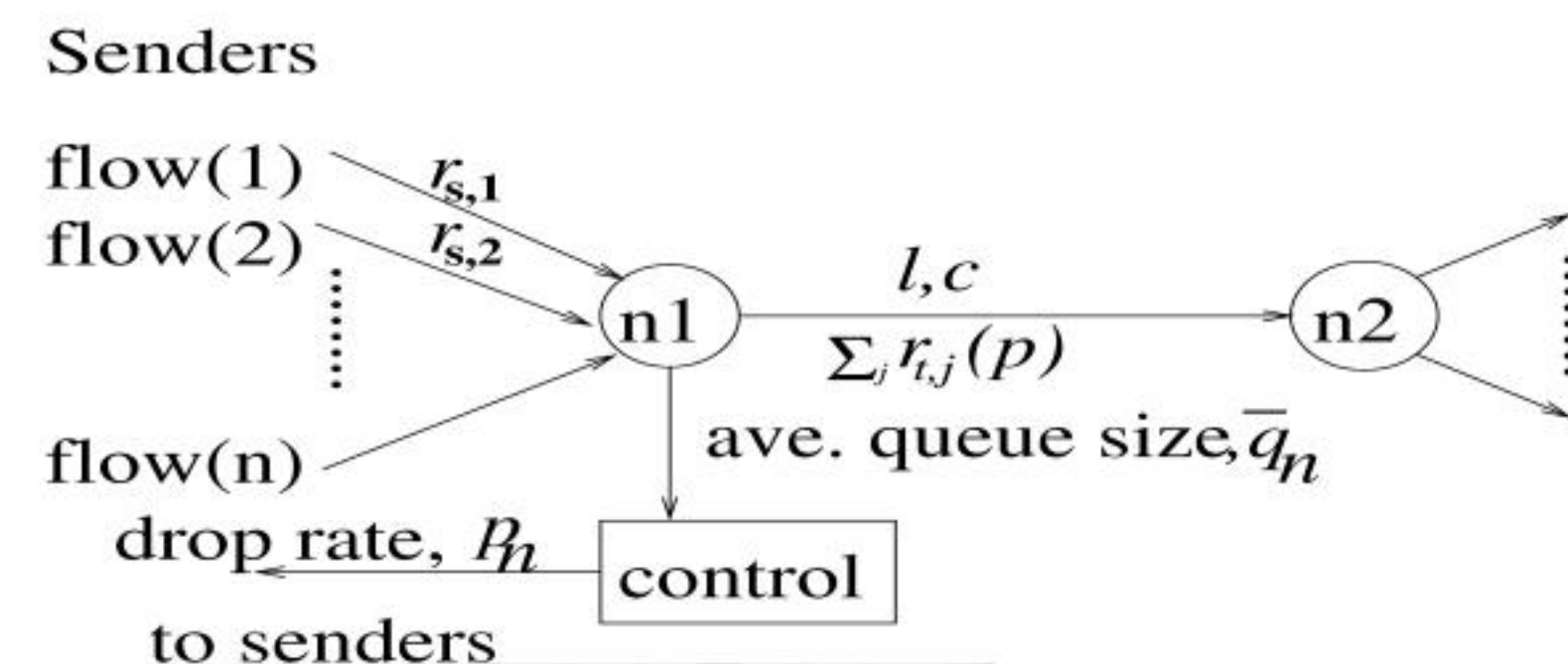


**Mathematical Modeling:**

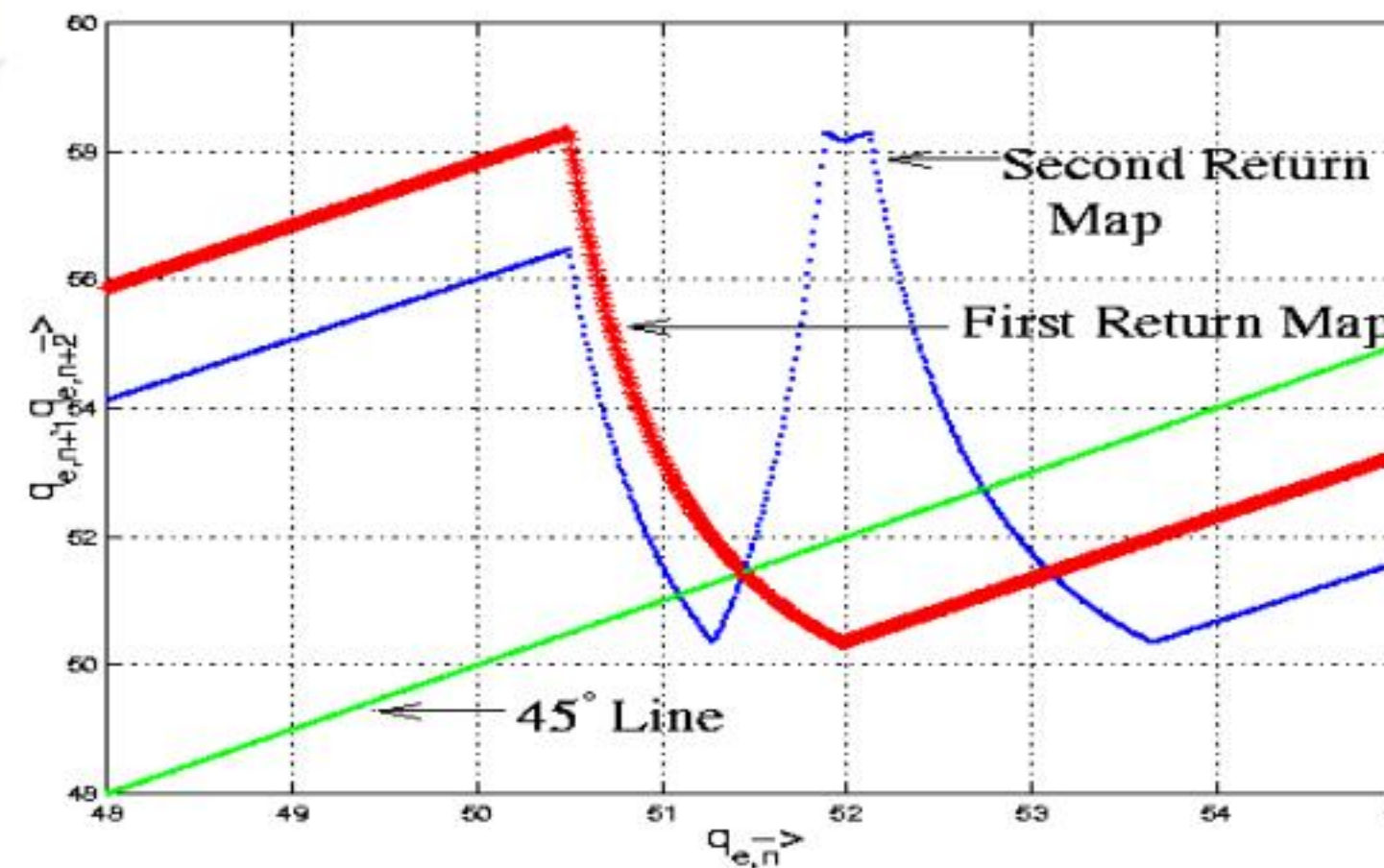
$$\begin{aligned}
 q_{k+1} &= G(p_k) \\
 \bar{q}_{e,k+1} &= A(\bar{q}_{e,k}, q_{k+1}) \\
 p_{k+1} &= H(\bar{q}_{e,k+1})
 \end{aligned}$$

- ✓ Essentially nonlinear first order discrete time dynamical system
- ✓ Nonlinearity comes from TCP transfer function, square root dependence on drop prob.
- ✓ Model as a self clocking system
- ✓ Piecewise smooth map

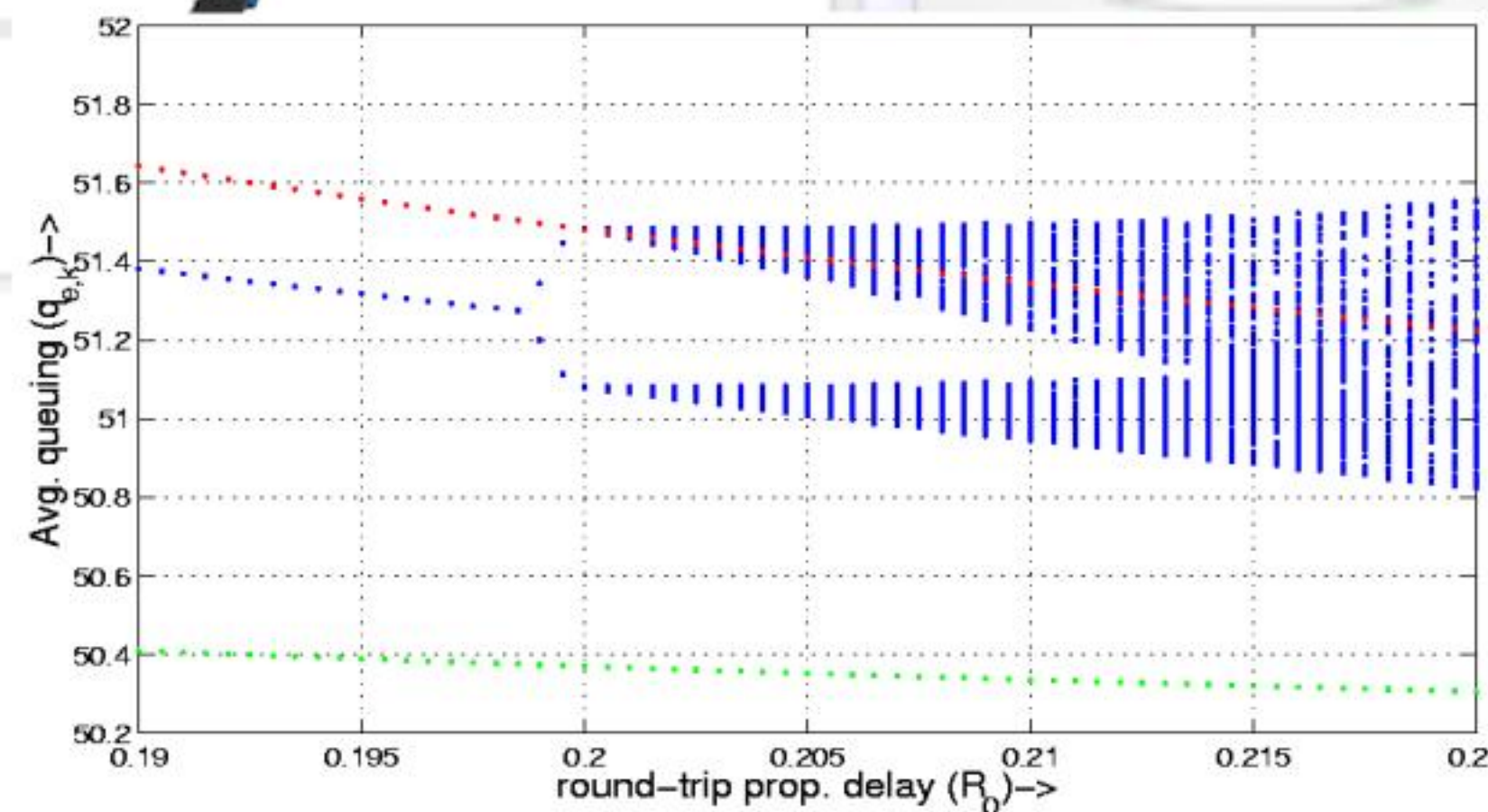
**Simplified one hop network model as a feedback system**



First and second return map and their intersection with 45 degree line show the existence of a fixed point and period two orbit



- ✓ Stability analysis of period doubling and dynamical stability criteria
- ✓ Provides stability criteria for emerging period two orbit
- ✓ Uses bifurcation diagrams to investigate the solutions as system parameters like number of connection (n), round trip time (R) and RED parameters like pmax, q\_min, q\_max and exponentially averaging weight (w) vary.
- ✓ Existence of primary bifurcation in the form of period doubling
- ✓ Secondary bifurcations like border collision
- ✓ Sequence of bifurcations leading to **Chaos**
- ✓ Sensitivity observed in practice can be reproduced from



Bifurcation diagram with respect to round trip delay  $R_0$ .

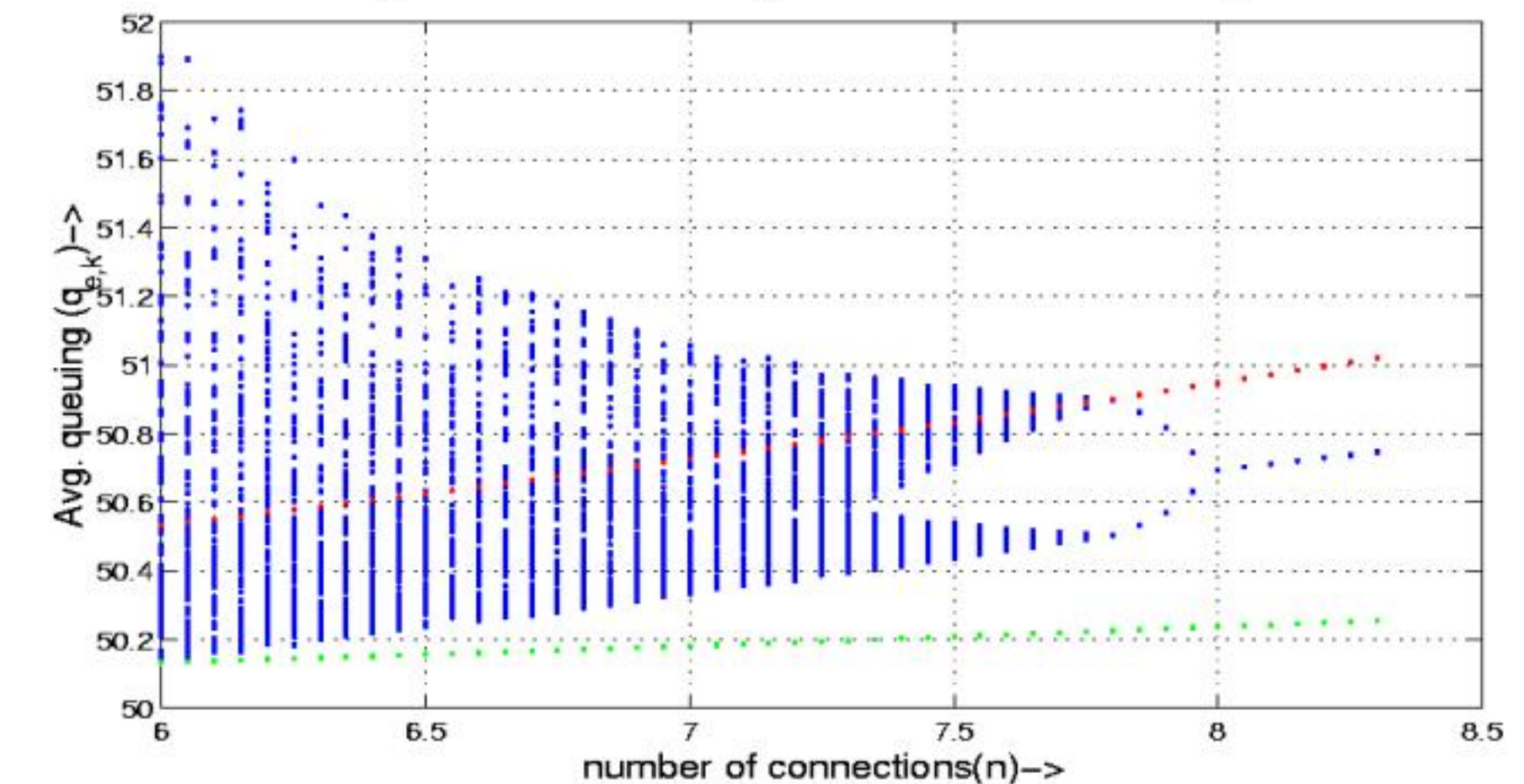
**One Dimensional First Order Discrete Time Map:**

$$\bar{q}_{e,k+1} = \begin{cases} (1-w)\bar{q}_{e,k} & \text{if } \bar{q}_{e,k} > b_1 \\ (1-w)\bar{q}_{e,k} + wB & \text{if } \bar{q}_{e,k} < b_2 \\ (1-w)\bar{q}_{e,k} + w\left(\frac{nK}{\sqrt{\frac{p_{max}(\bar{q}_{e,k}-q_{min})}{(q_{max}-q_{min})}} - \frac{R_0 c}{M}}\right) & \text{otherwise} \end{cases}$$

$$:= f(\bar{q}_{e,k}, \rho)$$

where  $\rho$  represents the parameter vector in the system.

- $n$  = Number of active TCP connections
- $M$  = Maximum segment size or packet size
- $R_0$  = Round trip time
- $K$  = Modeling constant between 1 and  $\sqrt{8/3}$
- $w$  = Exp. averaging weight
- $c$  = Bottleneck bandwidth



Bifurcation diagram with respect to number of TCP connections (n).

**Conclusion:**

Model successfully captures the dynamical phenomena of TCP networks with RED AQM and provides useful information about setting control parameters. It also gives insight to formulate new control mechanisms.

Reference: Nonlinear Instabilities of TCP-RED by P. Ranjan, E. H. Abed and R. La, Accepted for INFOCOM 2002.