

# Reconstruction from Magnitudes of Redundant Representations

Radu Balan, Department of Mathematics, CSCAMM, ISR and NWC



## Problem Formulation

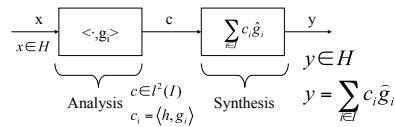
Typical signal processing pipeline:



Features:

- Relative low complexity  $O(N \log(N))$
- On-line version is possible

The Analysis/Synthesis Components:



Example: Short-Time Fourier Transform

$$c_{k,f} = \langle x, g_{k,f} \rangle \quad g_{k,f}(t) = e^{2\pi i f(t-kb)} g(t-kb)$$

$$I = \{k, f; k \in \mathbb{Z}, 0 \leq f \leq F-1\} = \mathbb{Z} \times \mathbb{Z}_F$$

$$H = l^2(\mathbb{Z})$$

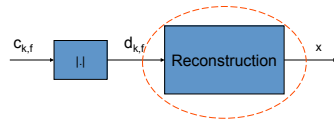
**Problem:**

Given the Short-Time Fourier Amplitudes (STFA):

$$d_{k,f} = \left| \langle x, g_{k,f} \rangle \right| = \left| \sum_{t=kb}^{kb+M-1} x(t) \overline{g(t-kb)} e^{-2\pi i f t F} \right|$$

we want an **efficient** reconstruction algorithm:

- Reduced computational complexity
- On-line ("on-the-fly") processing



Where is this problem important:

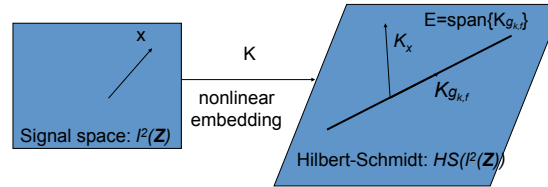
- Speech enhancement
- Speech separation
- Neural speech production
- X-Ray Crystallography
- Optical Communication

## Solution/Approach

**First observation [BBCE'09]:**

$$d_{k,f}^2 = \left| \langle x, g_{k,f} \rangle \right|^2 = \text{tr} \left\{ x x^* K_{g_{k,f}} K_{g_{k,f}}^* \right\} = \langle K_x, K_{g_{k,f}} \rangle_{HS}$$

$$K_x(y) = \langle y, x \rangle x \quad K_{g_{k,f}}(y) = \langle y, g_{k,f} \rangle g_{k,f}$$



Assume  $\{K_{g_{k,f}}\}$  form a frame for its span,  $E$ . Then the projection  $P_E$  can be written as:

$$P_E = \sum_{k,f} \left\langle \cdot, K_{g_{k,f}} \right\rangle_{HS} Q_{k,f}$$

where  $\{Q_{k,f}\}$  is the canonical dual of  $\{K_{g_{k,f}}\}$ .

Frame operator

$$X \mapsto S(X) = \sum_{k,f} \left\langle X, K_{g_{k,f}} \right\rangle_{HS} K_{g_{k,f}}$$

$$Q_{k,f} = S^{-1}(K_{g_{k,f}})$$

**Second Observation:** Since

$$g_{k,f} = M^f T^k g$$

where  $M : h \mapsto Mh(t) = e^{2\pi i f t F} h(t)$ ,  $T : h \mapsto Th(t) = h(t-b)$

it follows:

$$K_{g_{k,f}} = \Lambda^f \Theta^k K_g \quad Q_{k,f} = \Lambda^f \Theta^k Q_{0,0}$$

where  $\Lambda : X \mapsto \Lambda X = M X M^*$ ,  $\Theta : X \mapsto \Theta X = T X T^*$

Explicitly

$$(Q_{k,f})_{t_1, t_2} = e^{2\pi i f(t_1 - t_2) F} (Q_{0,0})_{t_1 - kb, t_2 - kb}$$

$$\text{Set: } H(\omega, m) = \sum_{k \in \mathbb{Z}} \sum_{f \in \mathbb{Z}_F} e^{2\pi i (k\omega + mf/F)} \left| \langle g, g_{k,f} \rangle \right|^2$$

**Main Result:**

**Theorem** Assume  $\{g_{k,f}\}_{(k,f) \in \mathbb{Z} \times \mathbb{Z}_F}$  is a frame for  $l^2(\mathbb{Z})$ .

Then  $\{K_{g_{k,f}}; (k,f) \in \mathbb{Z} \times \mathbb{Z}_F\}$

1. is a frame for its span in  $HS(l^2(\mathbb{Z}))$  iff for each  $m \in \mathbb{Z}_F$ ,  $H(\omega, m)$  either vanishes identically in  $\omega$ , or it is never zero;
2. is a Riesz basis for its span in  $HS(l^2(\mathbb{Z}))$  iff for each  $m \in \mathbb{Z}_F$  and  $\omega$ ,  $H(\omega, m)$  is never zero.

Under these hypotheses:

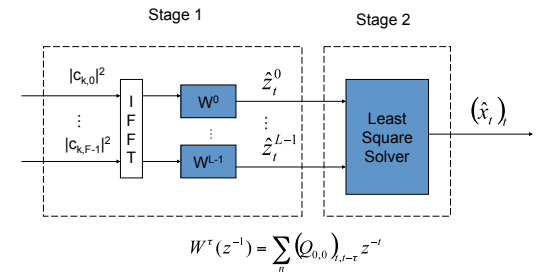
$$(Q_{0,0})_{t,t-\tau} = \frac{1}{F} \int_0^1 \sum_p g(p) g(p-\tau) e^{-2\pi i p \omega} d\omega$$

**Final step:** Signal reconstruction from  $Q_x$  by solving:

$$\min_x \left[ \|x\|^2 - (K_x)_{j,j} |x| + w_1 |x \hat{x}_{j-1} - (K_x)_{j,j-1}|^2 + \dots + w_j |x \hat{x}_{j-j} - (K_x)_{j,j-j}|^2 \right]$$

for  $x_t$ , assuming we already estimated  $x_s$  for  $s < t$ ,

## Reconstruction scheme:



**Example:**

