

Opinion Dynamics over Signed Social Networks

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Social Networks



Opinions

iPhone, Blackberry, or Samsung? Republican or Democrat? Sell or buy AAPL? The rate of economic growth this year? Social cost of carbon?



French 1956; Benerjee 1992; Galam 1996

Dynamics of Opinions

$$x_i(k+1) = f_i\left(x_i(k); x_j(k), j \in \mathcal{N}_i\right)$$



De Groot Social Interactions

- $\mathbf{x}(k+1) = \mathbf{P}\mathbf{x}(k)$
- ${f P}$ is a stochastic matrix



De Groot Social Interactions



De Groot Social Interactions

$$\mathbf{x}(k+1) = \mathbf{P}\mathbf{x}(k)$$

An agreement is achieved if $\, {f P}$ is ergodic in the sense that

$$\lim_{k \to \infty} x_i(k) = \mathbf{v}^\top \mathbf{x}(0)$$

Trust and cooperation lead to social consensus!

Wisdom of Crowds (with Trust)

Golub and Jackson 2010

A NEW YORK TIMES BUSINESS BESTSELLER

"As entertaining and thought-provoking as *The Tipping Point* by Malcolm Gladwell. . . . *The Wisdom of Crowds* ranges far and wide." —*The Boston Globe*

THE WISDOM OF CROWDS JAMES SUROWIECKI

WITH A NEW AFTERWORD BY THE AUTHOR



Disagreement Models

- Memory of initial values
 - Friedkin and Johnsen (1999)
- Bounded confidence
 - Krause (1997); Hegselmann-Krause (2002); Blondel et al. (2011); Li et al. (2013)
- Stubborn agents



- Acemoglu et al. (2013)
- Homophily

Dandekar et al.	(2013)
	(/

This Talk

A model and theory for opinion dynamics over social networks with friendly and adversarial interpersonal relations coexisting.

Friends and Adversaries



Structural Balance Theory

- Strongly balanced if the node set can be divided into two disjoint subsets such that negative links can only exist between them;
- Weakly balanced if such a partition contains maybe more than two subsets.



Heider (1947), Harary (1953), Cartwright and Harary (1956), Davis (1963)

Structural Balance



When do nodes interact?

Underlying World

$\mathbf{G}=\mathbf{G}^+\cup\mathbf{G}^-$



Gossip Model



Gossip Model

Independent with other time and node states, at time k, (i) A node i is drawn with probability 1/N; (ii) Node i selects one of its neighbor j with probability $1/|\mathcal{N}_i|$.

DOI:10.1145/2184319.2184338

A few hubs with many connections share with many individuals with few connections.

BY BENJAMIN DOERR, MAHMOUD FOUZ, AND TOBIAS FRIEDRICH

Why Rumors Spread So Quickly in Social Networks



How a pair of nodes interacts with each other when they meet?

Positive and Negative Interactions

A pair (i,j) is randomly selected. The two selected nodes update.







 $x_i(k+1) = x_i(k) + \beta (x_i(k) - x_j(k)) \qquad \beta > 0$



Positive and Negative Interactions



Mean/Mean-Square Evolution

Relative-State-Flipping Model

 $\mathbf{x}(k+1) = W(k)\mathbf{x}(k)$

$$\mathbb{E}\{W(k)\} = I - \alpha L_{\text{pst}}^{\dagger} + \beta L_{\text{neg}}^{\dagger}.$$

• It's an eigenvalue perturbation problem!

Phase Transition

Theorem. Suppose G^+ is connected and G^- is non-empty. Then there exists β_* such that

- (i) $\lim_{k\to\infty} \mathbb{E}\{x_i(k)\} = \sum_{i=1}^N x_i(0)/N \text{ for all } i = 1, \dots, N \text{ if } \beta < \beta_*;$
- (ii) $\lim_{k\to\infty} \max_{i,j} \|\mathbb{E}\{x_i(k)\} \mathbb{E}\{x_j(k)\}\| = \infty \text{ if } \beta > \beta_*.$
- It's possible to prove that the expectation of the state transition matrix is *eventually positive*.

Phase Transition

Let G be the complete graph. Let G^- be the Erdos-Renyi random graph with link appearance probability p.

(i) If p < α/(α+β), then
<p>P(Consensus in expectation) → 1
as the number of nodes N tends to infinity;

(ii) If p > α/(α+β), then
P(Divergence in expectation) → 1

as the number of nodes N tends to infinity.

Sample Path Behavior

Live-or-Die Lemma

Introduce

$$\mathscr{C}_{x^0} \doteq \left\{ \limsup_{k \to \infty} \max_{i,j} |x_i(k) - x_j(k)| = 0 \right\}, \quad \mathscr{D}_{x^0} \doteq \left\{ \limsup_{k \to \infty} \max_{i,j} |x_i(k) - x_j(k)| = \infty \right\}, \quad \mathscr{D}_{x^0}^* \doteq \left\{ \liminf_{k \to \infty} \max_{i,j} |x_i(k) - x_j(k)| = \infty \right\}$$

Lemma.

Suppose G⁺ is connected. Then (i) $\mathbb{P}(\mathscr{C}_{x^0}) + \mathbb{P}(\mathscr{D}_{x^0}) = 1$; (ii) $\mathbb{P}(\mathscr{C}_{x^0}) + \mathbb{P}(\mathscr{D}_{x^0}) = 1$. As a consequence, almost surely, one of the following events happens:

$$\{ \lim_{k \to \infty} \max_{i,j} |x_i(k) - x_j(k)| = 0 \}; \{ \lim_{k \to \infty} \max_{i,j} |x_i(k) - x_j(k)| = \infty \}; \{ \liminf_{k \to \infty} \max_{i,j} |x_i(k) - x_j(k)| = 0; \limsup_{k \to \infty} \max_{i,j} |x_i(k) - x_j(k)| = \infty \}.$$

Zero-One Law

$$\mathscr{C} \doteq \left\{ \limsup_{k \to \infty} \max_{i,j} |x_i(k) - x_j(k)| = 0 \text{ for all } x^0 \in \mathbb{R}^n \right\},$$

$$\mathscr{D} \doteq \left\{ \exists \text{ (deterministic) } x^0 \in \mathbb{R}^n, \text{ s.t. } \limsup_{k \to \infty} \max_{i,j} |x_i(k) - x_j(k)| = \infty \right\}$$

Theorem. Both \mathscr{C} and \mathscr{D} are trivial events (i.e., each of them occurs with probability equal to either 1 or 0) and $\mathbb{P}(\mathscr{C}) + \mathbb{P}(\mathscr{D}) = 1$.

No-Survivor Theorem

Theorem. There always holds

$$\mathbb{P}\left(\liminf_{k \to \infty} \left| x_i(k) - x_j(k) \right| = \infty \left| \liminf_{k \to \infty} \max_{i,j} \left| x_i(k) - x_j(k) \right| = \infty \right) = 1$$

for all $i \neq j$.

Phase Transition

Theorem.

(i) Suppose G^+ is connected. Then there is a $\beta_* > 0$ such that

$$\mathbb{P}\Big(\lim_{k \to \infty} x_i(k) = \sum_{i=1}^N x_i(0)/N\Big) = 1$$

for all i if $\beta < \beta_*$.

(ii) There is $\beta^* > 0$ such that

$$\mathbb{P}\left(\liminf_{k\to\infty}\max_{i,j}\left\|x_i(k)-x_j(k)\right\|=\infty\right)=1$$

for all i if $\beta > \beta^*$.

Bounded State Model

Bounded States

- Let A > 0 be a constant and define $\mathscr{P}_A(\cdot)$ by $\mathscr{P}_A(z) = -A, z < -A, \mathscr{P}_A(z) = z, z \in [-A, A]$, and $\mathscr{P}_A(z) = A, z > A$.
- Define the function $\theta : E \to \mathbb{R}$ so that $\theta(\{i, j\}) = \alpha$ if $\{i, j\} \in E^+$ and $\theta(\{i, j\}) = -\beta$ if $\{i, j\} \in E^-$.

Consider the following node interaction under relative-state flipping rule:

$$x_{s}(t+1) = \mathscr{P}_{A}((1-\theta)x_{s}(t) + \theta x_{-s}(t)), \ s \in \{i, j\}.$$

Clustering of Opinions

Theorem. Let $\alpha \in (0, 1/2)$. Assume that G is a weakly structurally balanced complete graph under the partition $V = V_1 \cup V_2 \cdots \cup V_m$ with $m \ge 2$. Let $\alpha \in (0, 1/2)$. When β is sufficiently large, almost sure boundary clustering is achieved in the sense that for almost all initial value $\mathbf{x}(0)$ w.r.t. Lebesgue measure, there are there are m random variables, $l_1(\mathbf{x}(0)), \ldots, l_m(\mathbf{x}(0))$, each of which taking values in $\{-A, A\}$, such that:

$$\mathbb{P}\left(\lim_{t \to \infty} x_i(t) = l_j(\mathbf{x}(0)), \ i \in \mathcal{V}_j, \ j = 1, \dots, m\right) = 1.$$

Separation Events



• The power of minority groups.

Numerical Example



Oscillation of Opinions

Theorem. Let $\alpha \in (0, 1/2)$. Assume that G is a complete graph and the positive graph G⁺ is connected. When β is sufficiently large, for almost all initial value $\mathbf{x}(0)$ w.r.t. Lebesgue measure, there holds for all $i \in V$ that

$$\mathbb{P}\Big(\liminf_{t \to \infty} x_i(t) = -A, \ \limsup_{t \to \infty} x_i(t) = A\Big) = 1.$$

Numerical Example





Related Publications

Shi et al. 2013 IEEE Journal on Selected Areas in Communications; Shi et al. 2015, 2016 IEEE Transactions on Control of Network Systems; Shi et al. 2016 Operations Research.

Thank you!